

# Regression analysis

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- Highly **incomplete and fragmented** introduction to regression analysis.
- Have **data** on  $y$  and  $x$  ( $x$  is high dimensional vector) and would like to:
  - Study **correlation** between  $y$  and elements of  $x$ .
  - Use  $x$  to **forecast, predict or impute**  $y$ .
  - Understand how much of **variation** in  $y$  is "explained" by  $x$ .
  - Estimate **causal impact** of  $x$  on  $y$  after controlling for confounding factors

# Introduction (2)

- Elements of  $X$ .
  - Can be **continuous or discrete**.
  - May be **measured with error** (this causes problems).
- Elements of  $Y$ .
  - Can be continuous.
  - Can be discrete.
    - Usually requires a **non-linear** model.
    - However, researchers often use the linear probability model.
    - It is much better to use a discrete outcome model.
  - May be measured with error (this is less of a problem).
  - May be censored or truncated.
    - Usually requires use of **non-linear** model.

## 1 Parametric methods

- 1 Ordinary least squares
- 2 Maximum likelihood
- 3 Method of moments
- 4 Quantile regression
- 5 Bayesian methods

## 2 Semi- and Non-parametric methods

- Allow "parameters" to be infinite dimensional.
- Estimate  $E[Y|X] = f(X)$  to be an unknown function instead of a known one like  $x\beta$ .
- Estimate probability density function of  $x$  rather than estimate mean and variance.

## Basic linear model (notation)

- **Data** on  $(y_i, x_i)$  for  $i = 1, \dots, N$  where  $y_i \in \mathbf{R}$  and  $x_i \in \mathbf{R}^k$ .
- Let  $Y = (y_1, \dots, y_N)^T$  be a  $(N \times 1)$  vector of **outcomes** and let  $X$  be an  $(N \times K)$  matrix of **regressors**. That is,

$$X = \begin{bmatrix} x_1(1) & \cdots & x_1(K) \\ \vdots & & \vdots \\ x_N(1) & \cdots & x_N(K) \end{bmatrix}.$$

- Let  $\varepsilon = (\varepsilon_1, \dots, \varepsilon_N)$  be an  $(N \times 1)$  vector of **errors** or **unobserved variables**.

- The **linear model** is

$$Y = X\beta + \varepsilon$$

where  $\beta$  is a  $(K \times 1)$  vector of **parameters** to be estimated.

- Usually the model includes a constant so that  $x_i(1) = 1$  for all  $i$ .
- Key restriction is that the model is linear in  $\beta$  (can allow for example  $x$  and  $x^2$  or  $\log(x)$ .)
- $X$  may include "dummy" variables that indicate membership in a group. For, example  $x_i(2) = 1$  if  $i$  is female and  $x_i(2) = 0$  otherwise.

# Basic linear model (goals)

- **Goals:**

- **Unbiased** or **consistent** estimates of  $\beta$ .
- **Prediction** of  $Y$ .
- **Analysis of variance** of  $Y$ .
- **Test of hypotheses** about  $\beta$ .

# Basic linear model (problems)

- ➊ **Mis-specification.** Suppose the correct model is not linear?
  - ➊ Non-linear models or discrete outcomes.
  - ➋ Censoring or truncation of of outcomes
- ➋ **Endogeneity.** What if  $X$  is correlated with  $\varepsilon$ ?
  - ➊ Omitted variables.
  - ➋ Measurement error.
  - ➌ Joint causation.
- ➌ **High dimensional data.** What can one do if  $K$  is large?
- ➍ **Robustness.** How to reduce influence of outliers in data?
- ➎ **Correlation in errors.** How do you correct for correlation in errors?
- ➏ **Non-random sample.** How does one weight the data?



- **Ordinary least squares.** Choose  $\beta$  to solve the least squares problem

$$\min_{\{\beta\}} \left\{ 0.5 (Y - X\beta)^T (Y - X\beta) \right\}$$

- **First order conditions** are

$$X^T X \beta - X^T Y = 0.$$

- **Estimator** of  $\beta$  is

$$\hat{\beta} = (X^T X)^{-1} X^T Y$$

- Requires that  $X^T X$  has rank  $K$ .

# Properties of estimator (unbiased)

- **Assume** that

$$E[\varepsilon | X] = 0.$$

- **Then**

$$\begin{aligned} E[\widehat{\beta} | X] &= E\left[(X^T X)^{-1} X^T Y | X\right] \\ &= E\left[(X^T X)^{-1} X^T (X\beta + \varepsilon) | X\right] \\ &= E\left[(X^T X)^{-1} (X^T X) | X\right] \beta + E[\varepsilon | X] \\ &= \beta. \end{aligned}$$

# Asymptotic normality

- Further, **assume** that

$$V(\varepsilon | X) = \sigma^2 I.$$

- **Then**

$$V(\hat{\beta}) = \hat{\sigma}^2 (X^T X)^{-1}$$

where

$$\hat{\sigma}^2 = \frac{1}{n} \hat{e}^T \hat{e}$$

is estimate of variance of error. and where

$$\hat{e} = Y - X\hat{\beta}.$$

- In a **large sample**, (under very general conditions), the **central limit theorem** can be used to show that

$$\sqrt{N} (\hat{\beta} - \beta) \xrightarrow{A} N(0, \hat{\Sigma}).$$

# Confidence intervals and hypothesis tests

- These results can be used to construct confidence intervals for  $\beta$  and to conduct hypothesis tests.
- When  $\beta$  is a scalar, a **95% confidence interval** for  $\beta$  is

$$\hat{\beta} \pm 1.96\hat{\sigma}_{\beta}.$$

- **Test the hypothesis** that  $\beta_1 + \beta_2 = 0$ .
  - 1 Let  $s = \beta_1 + \beta_2$ .
  - 2 Then  $\hat{s} = \hat{\beta}_1 + \hat{\beta}_2$  converges in distribution to a normal random variable with mean  $s = \beta_1 + \beta_2$  and variance  $\sigma_s^2 = \sigma_{11} + \sigma_{22} + 2\sigma_{12}$ .
  - 3 **Reject the hypothesis** if  $\frac{\hat{s}}{\hat{\sigma}_s} \geq 1.96$ .

- **Best predictor** of  $Y$  is

$$E[Y|X] = X\hat{\beta}.$$

- Minimises the sum of squared prediction errors.

## Goodness of fit

- **Coefficient of determination** or  $R^2$  measures the fraction of variance of the outcome that is explained by the model. It is

$$R^2 = 1 - \frac{e^T e}{(y - \bar{y})^T (y - \bar{y})}.$$

- A measure of "**Goodness-of-fit**".
- When  $R^2$  is near zero, then most of variance is explained by errors.
- When near one, most of variance is explained by model.
- When variables are added to model,  $R^2$  increases. So, researchers often used "adjusted  $R^2$ "

$$\bar{R}^2 = 1 - (1 - R^2) \frac{n - 1}{n - k - 2}$$

which adjusts  $R^2$  for the number of variables in the model.

- 1 Maximum likelihood estimation.
  - Linear models.
  - Nonlinear models.
  - Discrete outcomes.
- 2 Instrumental variables methods.
- 3 Systems of equations.
- 4 Penalized methods.